

Integrated systems are pre-configured with hardware for real-time data collection and to meet your specific requirements:

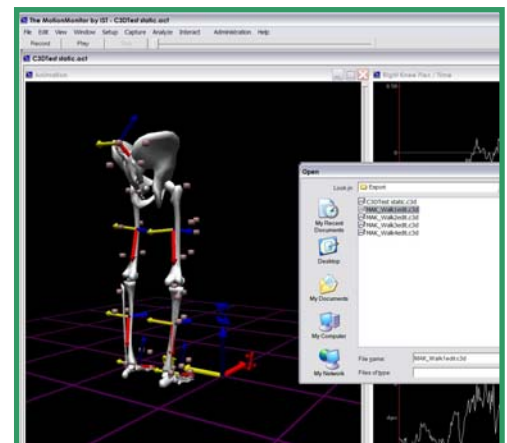
The MotionMonitor™ is a turn-key 3-D motion capture system designed to synchronously collect data from kinematic trackers, EMG, force plates, video, event markers and other analog devices. Data generated from a rich collection of analytical tools are immediately available for playback with graphical displays of all data outputs. Stunning 3-D computer-rendered animations of the subject can be viewed as a skeleton, stick figure, or humanoid. Real-time measurement of the human body's movement, muscle recruitment and external forces acting on the body is achieved using the broadest range of hardware available in the market.



- Ascension's FOB, MiniBirds, MotionStar and driveBay
- Polhemus' Fastrak, Patriot and Liberty
- Motion Analysis Corp's Hawk and Eagle Cameras
- Qualisys' ProReflex and Oqus Cameras
- PhaseSpace's Impulse
- Northern Digital's Optotrak 3020 and Certus
- Organic Motion's BioStage
- Bertec, AMTI and Kistler force plates
- ATI, AMTI and Bertec mini-load cells
- All analog EMG systems
- Eyelink II eye tracking system
- Phantom Haptic devices
- Virtual Reality Displays
- Single/Multiple Video Cameras

Analyze Data collected from any hardware using The MotionMonitor C3D Model Builder:

- Import C3D motion and analog data and construct models in 4 simple steps
- Use marker sets and rigid bodies, established or user-defined
- Define virtual joint centers, landmarks & segment coordinate systems
- Define hip and shoulder joint centers using functional methods
- Apply the ISB Shoulder Protocol
- Save model templates for faster setup



contact us for more information:

(773) 244-6470

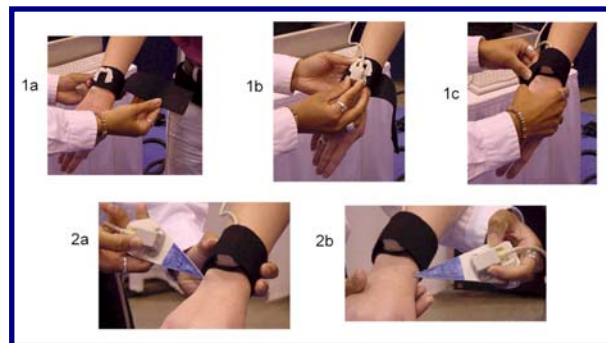
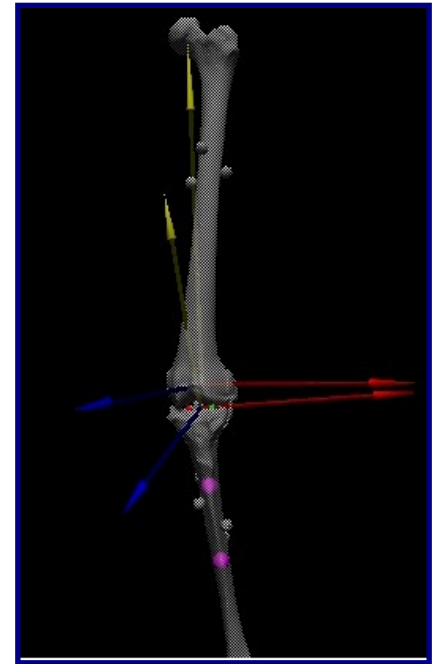
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Subject set-up designed to meet your unique requirements:

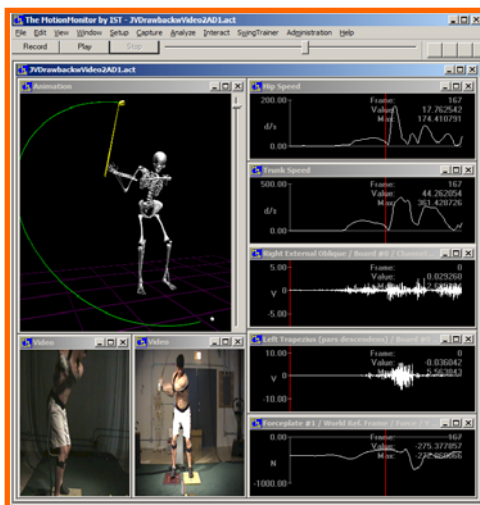


- Create a stylus to assist in precise digitization of anatomical landmarks
- Define a Global World Axes consistent with your research protocol
- Align axes of force plates and hand transducers with global axes
- Use quick release sensor cuffs for a faster and more consistent subject set-up
- Digitize landmarks and track virtual joint centers
- Determine joint centers and segment orientation using accepted protocols such as the Bell, Davis or Functional methods for hip and shoulder joint centers
- Or, extract joint centers, local coordinate systems and landmarks automatically from CT or MRI reconstructions as shown in the image on the right



Powerful control of data collection:

- Event driven triggers for exact start or end of data collection
- Autosave/Autaname features for hands-free data collection
- Event on-set and duration tracked using a choice of hardware switches such as IR, LEDs and FSRs
- User defined software switches for contingent start or end conditions
- Automatic synchronization of data collected from devices with different sampling rates

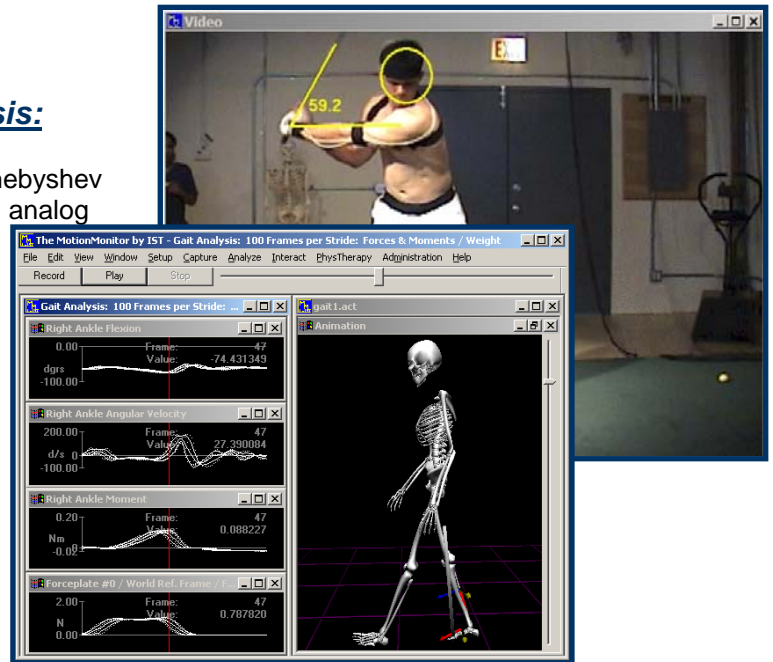


Immediate playback ensures accurate collection of data:

- No digitizing, post-processing or lost markers
- All kinematic and kinetic data are user-selectable from drop-down menus with no programming required
- New variables can be defined using standard mathematical notation including vector and matrix operations
- Force plate data includes COP, forces and moments
- EMG signals include Raw, RMS, Power Spectrum and Exposure Variance Analysis
- Joint power and work
- Helical Axes

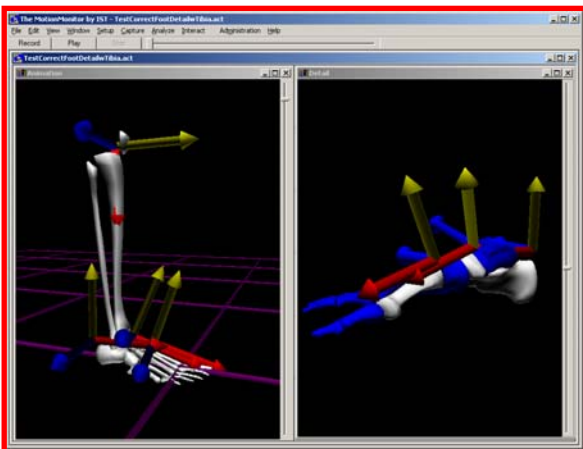
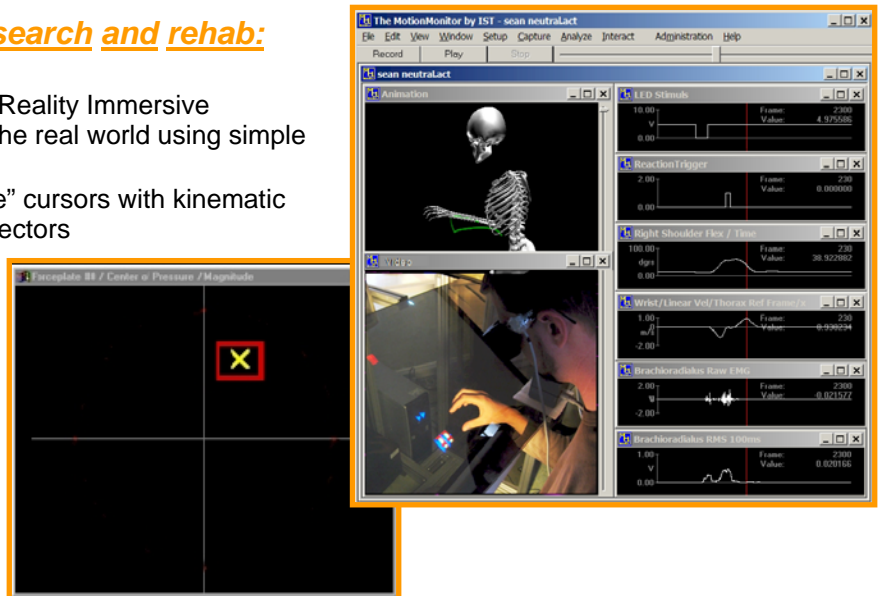
Data Reduction features will speed analysis:

- Employ analog filters such as Butterworth and Chebyshev with cut-off frequencies for each sensor and each analog channel
- Use Bandpass filters in the frequency domain
- Apply user-defined, Dempster or Zatsiorsky anthropometric assumptions
- Define segment local axes and orientation
- Automatically or manually define events in post-processing
- Normalize activities in time or by subject height and mass
- Perform ensemble averaging with added statistical outputs
- View all data in frequency or time domain
- Use real-time drawing tools with synchronized video



Biofeedback for motor control, neuro research and rehab:

- Present stimuli on 2-D monitors, Virtual Reality Immersive stereoscopic displays or at locations in the real world using simple drop down menus
- Control the position of tracking or “chase” cursors with kinematic position, EMG, analog signals or gaze vectors
- Audio, visual or analog output signals are generated based on proximity of “chase” cursor to targets
- Perturbate targets or “chase” variables with user defined “gain” formulas
- Apply assistive or resistive force feedback using single or dual haptic devices



Additional features to enhance your productivity:

- Use pre-defined protocols such as ISB Shoulder and Ankle protocol
- Preference files designed for specific applications such as gait and balance
- Detail module for tracking individual bones on the hand, foot and spine
- Meshfile generator to create images from CT & MRI scans
- User-defined calculations to eliminate the need for additional processing of data
- Scripting functions to facilitate complex data collection

Benefit from unparalleled commitment to post-sale support:

- All systems are installed on-site and “plug-in-the-wall ready”
- On-site training is provided to maximize value for your purchase and facilitate data collection
- Maintenance, Subscription and Support programs ensure that the product you buy today remains state of the art

What's new in The MotionMonitor Version 8....

<i>Features</i>	<i>Improved</i>	<i>New</i>
<i>The MotionMonitor C3D Model Builder for import of data from all hardware</i>	X	
<i>Support for Multi-sensored Body Segments in the C3D Model Builder</i>		X
<i>Support for ISB Shoulder Protocol in the C3D Model Builder</i>		X
<i>Support for Bertec's Split-belt Instrumented Treadmill</i>		X
<i>Support for AMTI's Instrumented Walker for upper extremity forces</i>		X
<i>Real-Time support for MAC & Qualisys passive optical cameras</i>	X	
<i>Real-Time support for PhaseSpace Impulse active optical system</i>		X
<i>Stream Fixed-Marker Sets from optical systems</i>		X
<i>Biofeedback Module for Immersive Virtual Reality Displays</i>	X	
<i>Support for user-defined objects in VR Displays</i>		X
<i>Support for Phantom Haptic Devices</i>	X	
<i>Support for Dual-Phantom Haptic Devices</i>		X
<i>Enhanced integration with Eyelink II includes definition of floors, walls, desks and other planes</i>	X	
<i>Additional Eyelink II data such as blinks, saccades, fixations and pupil diameter</i>		X
<i>Expanded User Defined Data functionality – vector, matrix, Boolean, offset operators in addition to math, trig and calculus</i>	X	
<i>Additional telestrator functions for integrated video includes computation of areas and lengths</i>	X	
<i>User-defined protocols for defining and naming landmarks for digitizing</i>	X	
<i>Scripting functions to facilitate complex data collection using a series of preference files</i>	X	
<i>Modify setup parameters such as world axes and force plate axes in post-processing</i>	X	
<i>Modify local segment axes' position and orientation in post-processing</i>		X
<i>Register CT/MRI scans for tracking internal landmarks both in-vitro and in-vivo during collection of activities and to define bone geometry</i>	X	
<i>Output data in real-time as either analog signal, TTL pulse or raw/processed variables over TCP/IP</i>		X